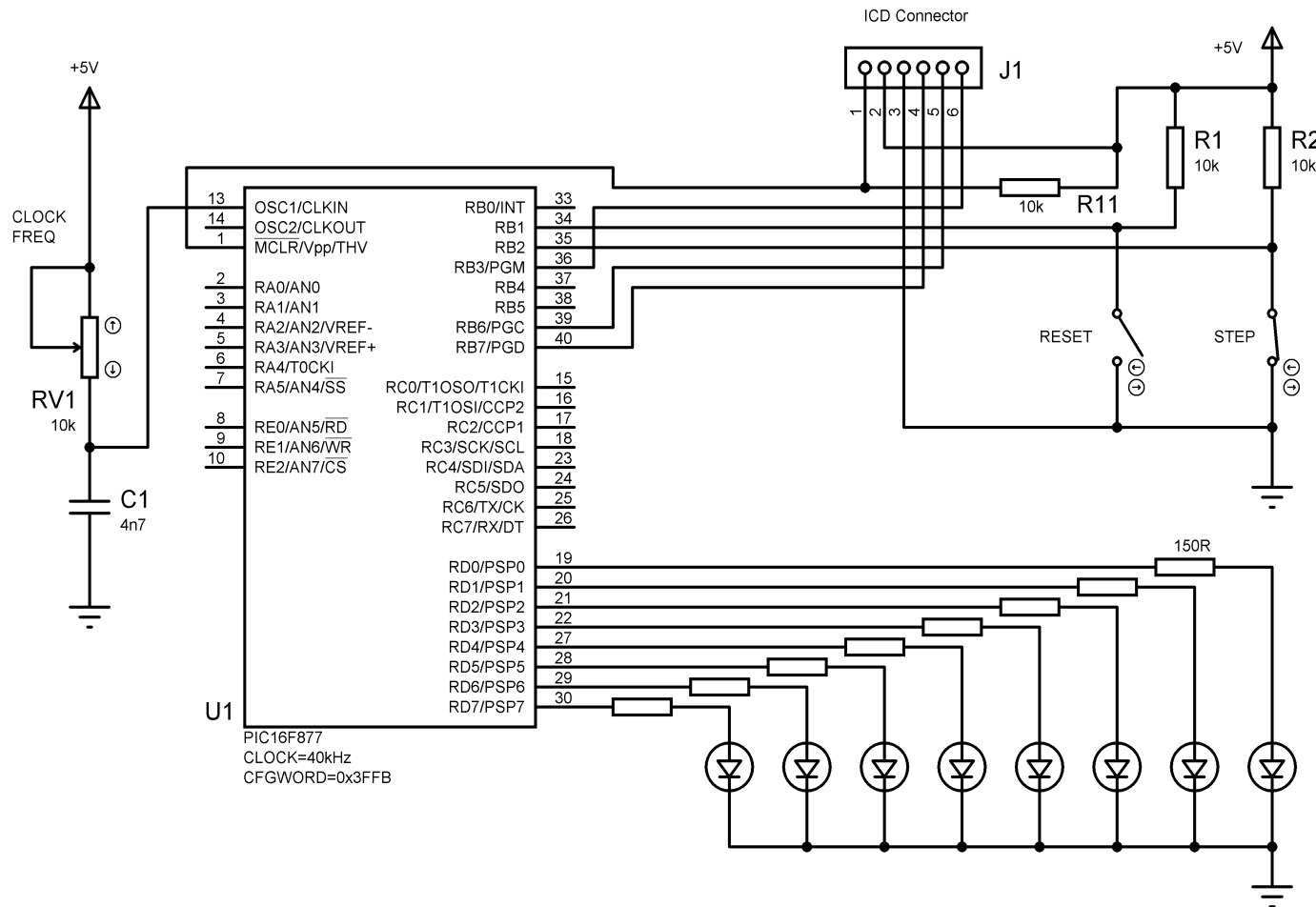


Interfacing PIC Microcontrollers

LED2 Schematic



- Application LED2 demonstrates the simplest forms of input and output
- Simple manual switched inputs produce logic high and low inputs
- The LEDs light up when the output is high. The PIC outputs can produce up to 25mA
- The simple RC clock components control the MCU operating frequency
- The ICD connector allows the PIC programming module to be attached for machine code downloading

Interfacing PIC Microcontrollers

LED2 Source Code

```

//////////////////////////
;
;   Source File:      LED2.ASM
;   Author:          MPB
;   Date:            2-1-13
;
;
;
;
;   Slow output binary count is stopped, started
;   and reset with push buttons.
;
;   Processor:      PIC 16F877A
;
;   Hardware:       Prototype
;   Clock:          RC = 40kHz
;   Inputs:         Port B: Push Buttons
;                   RB1, RB2 (active low)
;   Outputs:        Port D: LEDs (active high)
;
;   WDTimer:        Disabled
;   PUTimer:        Enabled
;   Interrupts:     Disabled
;   Code Protect:   Disabled
;
;
;
;   PROCESSOR 16F877      ; Define MCU type
;   ___CONFIG 0x3733     ; Set config fuses
; Register Label Equates.....
;
;   PORTB EQU 06      ; Port B Data Register
;   PORTD EQU 08      ; Port D Data Register
;   TRISD EQU 88      ; Port B Direction Register
;   Timer EQU 20      ; GPR used as delay counter
;
; Input Bit Label Equates .....
;
;   Inres EQU 1      ; 'Reset' input button = RD0
;   Inrun EQU 2      ; 'Run' input button = RD1

```

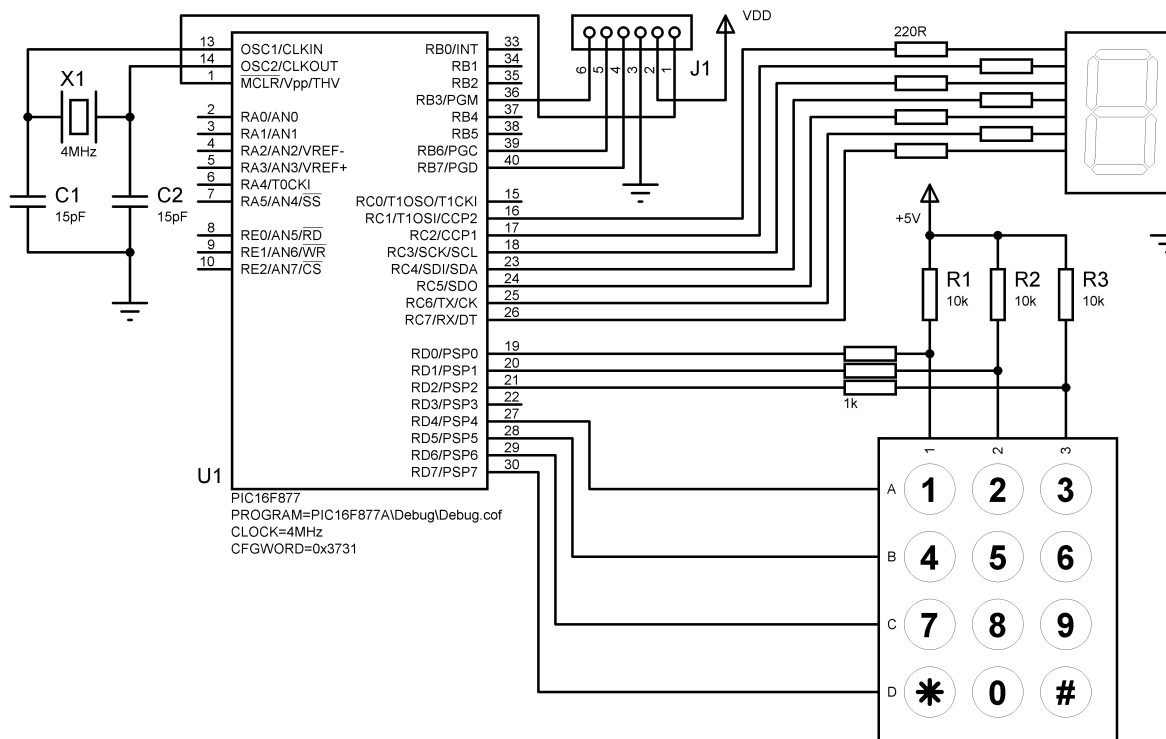
```

//////////////////////////
;
;   CODE 0      ; Program code start address
;
;   Initialise Port B (Port A defaults to inputs).....
;
;   BANKSEL TRISD      ; Select bank 1
;   MOVLW  b'00000000'  ; Port B Direction Code
;   MOVWF  TRISD      ; Load the DDR code into F86
;   BANKSEL PORTD      ; Select bank 0
;   GOTO   reset       ; Jump to main loop
;
; 'delay' subroutine .....
;
;   delay MOVWF Timer      ; Copy W to timer register
;   down  DECFSZ Timer     ; Decrement timer register
;         GOTO   down      ; and repeat until zero
;         RETURN          ; Jump back to main program
;
; Start main loop .....
;
;   reset CLRF  PORTD     ; Clear Port B Data
;
;   start BTFSS PORTB,Inres ; Test reset button
;         GOTO  reset      ; and reset Port B if pressed
;         BTFSC PORTB,Inrun ; Test run button
;         GOTO  start      ; and repeat if n pressed
;
;         INCF  PORTD      ; Increment output at Port B
;         MOVLW 0FF        ; Delay count literal
;         CALL  delay      ; Jump to subroutine 'delay'
;         GOTO  start      ; Repeat main loop always
;
;   END      ; Terminate source code

```

Interfacing PIC Microcontrollers

KEYPAD2 Schematic



- Application KEYPAD2 demonstrates simple keypad and display interfacing
- The keypad has switches arranged in rows and columns, scanned by outputting a logic low on each row and reading the each column input in turn
- A suitable seven segment code is selected output to the LED display
- The crystal clock produces a more precise clock frequency
- No clock components are needed if using 16F887 when the internal clock is selected

Interfacing PIC Microcontrollers

KEYPAD2 Source Code

```
;;;;;;;;;;;;;
;
;   KEYPAD2.ASM   MPB   11-01-13
;
;   Reads keypad and shows digit on display
;   Updated for VSM v8
;
;;;;;;;;;;;;;

        PROCESSOR 16F877

PCL      EQU    002        ; Program Counter
STATUS  EQU    003        ; Status register
PORTC   EQU    007        ; 7-Segment display
PORTD   EQU    008        ; 3x4 keypad
Timer   EQU    020        ; Delay counter

TRISC   EQU    087        ; Data direction
TRISD   EQU    088        ; registers

Key     EQU    021        ; Count of keys

; Code start.....

        CODE    0          ; code start
        NOP                    ; ICPD location

; Initialise ports.....

        BANKSEL TRISC        ; Display
        CLRW                    ; all outputs
        MOVWF TRISC          ;
        MOVLW B'00000111'    ; Keypad
        MOVWF TRISD          ; bidirectional

        BANKSEL PORTC        ; Display off
        CLRF PORTC           ; initially
        MOVLW B'11111111'    ; Set all outputs
        MOVWF PORTD          ; to keypad high
        GOTO main            ; jump to main
```

```
; Subroutines.....

delay   CLRF   Timer
count   DECFSZ Timer
        GOTO   count
        RETURN

; Check a row of keys .....

row     INCF   Key           ; Count first key
        BTFSS  PORTD,0      ; Check key
        GOTO   found        ; and quit if on

        INCF   Key           ; and repeat
        BTFSS  PORTD,1      ; for second
        GOTO   found        ; key

        INCF   Key           ; and repeat
        BTFSS  PORTD,2      ; for third
        GOTO   found        ; key
        GOTO   next         ; go for next row

; Scan the keypad.....

scan    CLRF   Key           ; Zero key count
        BSF   STATUS,0      ; Set Carry Flag
        MOVLW B'11111111'  ; Set all outputs
        MOVWF PORTD        ; to keypad high
        BCF   PORTD,4      ; Select first row
        GOTO   row         ; Check first row

next    BSF   PORTD,3       ; Set fill bit
        RLF   PORTD        ; Select next row
        BTFSC STATUS,0     ; 0 into carry flag?
        GOTO   row         ; if not, next row
        GOTO   scan        ; if so, start again

found   CALL   delay        ; debounce delay
        BTFSS  PORTD,0      ; await button release
        GOTO   found
        BTFSS  PORTD,1
        GOTO   found
        BTFSS  PORTD,2
        GOTO   found
        RETURN              ; quit with key count
```

KEYPAD2 Source Code (continued)

```
; Display code table.....
table  MOVF   Key,W           ; Get key count
      ADDWF  PCL             ; and calculate jump
      NOP                    ; into table
      RETLW  B'00001100'     ; Code for '1'
      RETLW  B'10110110'     ; Code for '2'
      RETLW  B'10011110'     ; Code for '3'
      RETLW  B'11001100'     ; Code for '4'
      RETLW  B'11011010'     ; Code for '5'
      RETLW  B'11111000'     ; Code for '6'
      RETLW  B'00001110'     ; Code for '7'
      RETLW  B'11111110'     ; Code for '8'
      RETLW  B'11001110'     ; Code for '9'
      RETLW  B'10010010'     ; Code for '*'
      RETLW  B'01111110'     ; Code for '0'
      RETLW  B'11101100'     ; Code for '#'

; Output display code.....
show   CALL   table          ; Get display code
      MOVWF  PORTC          ; and show it
      RETURN

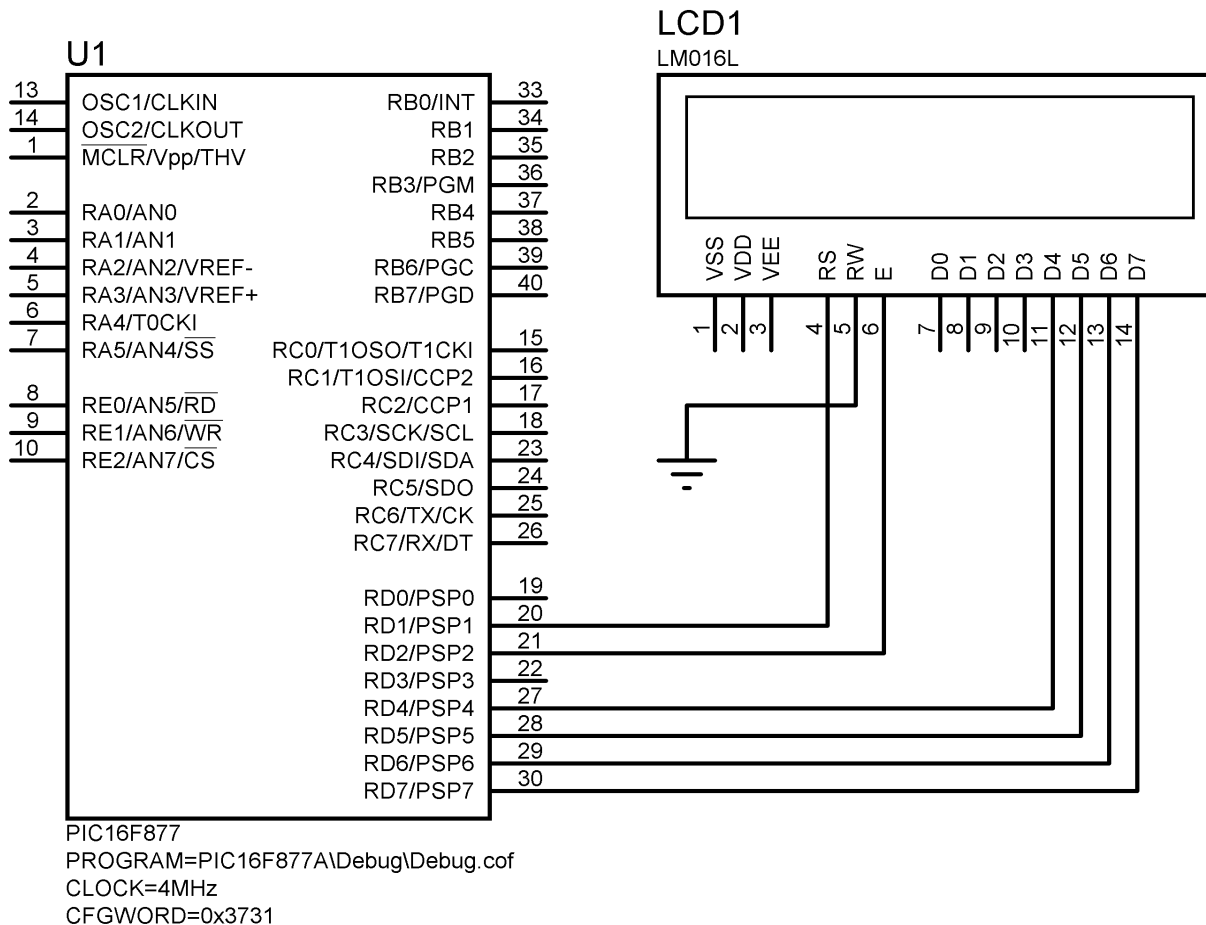
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

; Read keypad & display....
main   CALL   scan           ; Get key number
      CALL   show           ; and display it
      GOTO  main           ; and repeat
      END

;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
```

Interfacing PIC Microcontrollers

LCD2 Schematic



- Application LCD2 demonstrates the connection of an LCD alphanumeric display
- It can operate with a 4 or 8 bit input. In this case, the ASCII text codes are input as 2x4 bit nibbles
- The program generates a fixed message and a calculated incrementing count
- The simulation does not need the clock components to be included in the schematic

Interfacing PIC Microcontrollers

LCD2 Source Code

```
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
;
; LCD2.ASM      MPB      11-01-13
;
; Outputs fixed and variable characters
; to 16x2 LCD in 4-bit mode
; Updated for Proteus VSM v8
;
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

PROCESSOR 16F877A
; Clock = XT 4MHz, standard fuse settings
__CONFIG 0x3731

; LABEL EQUATES
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

INCLUDE "P16F877A.INC"; Standard register labels

Timer1 EQU 20      ; lms count register
TimerX EQU 21      ; Xms count register
Var EQU 22         ; Output variable
Point EQU 23       ; Program table pointer
Select EQU 24      ; Copy of RS bit
OutCod EQU 25      ; Temp store for output code

RS EQU 1           ; Register select output bit
E EQU 2            ; Display enable

; Program code ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

CODE 0             ; Place machine code
NOP                ; for ICD mode

BANKSEL TRISD     ; Select bank 1
CLRW               ; All outputs
MOVWF TRISD       ; Initialise display port
BANKSEL PORTD     ; Select bank 0
CLRWF PORTD       ; Clear display outputs

GOTO Start        ; Jump to main program
```

```
; SUBROUTINES ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

; lms delay with lus cycle time (1000 cycles).....

Onems  MOVLW  D'249'      ; Count for lms delay
        MOVWF  Timer1    ; Load count
Loop1  NOP                ; Pad for 4 cycle loop
        DECFSZ Timer1    ; Count
        GOTO   Loop1     ; until Z
        RETURN           ; and finish

; Delay Xms, X received in W .....

Xms    MOVWF  TimerX     ; Count for X ms
LoopX  CALL   Onems      ; Delay lms
        DECFSZ TimerX    ; Repeat X times
        GOTO   LoopX     ; until Z
        RETURN           ; and finish

; Generate data/command clock signal E .....

PulseE BSF     PORTD,E   ; Set E high
        CALL   Onems     ; Delay lms
        BCF   PORTD,E   ; Reset E low
        CALL   Onems     ; Delay lms
        RETURN          ; done

; Send a command byte in two nibbles from RB4 - RB7 .....

Send   MOVWF  OutCod     ; Store output code
        ANDLW  0F0        ; Clear low nybble
        MOVWF  PORTD     ; Output high nybble
        BTFSC Select,RS ; Test RS bit
        BSF   PORTD,RS  ; and set for data
        CALL  PulseE    ; and clock display register
        CALL  Onems     ; wait lms for display

        SWAPF OutCod     ; Swap low and high nybbles
        MOVF  OutCod,W   ; Retrieve output code
        ANDLW  0F0        ; Clear low nybble
        MOVWF  PORTD     ; Output low nybble
        BTFSC Select,RS ; Test RS bit
        BSF   PORTD,RS  ; and set for data
        CALL  PulseE    ; and clock display register
        CALL  Onems     ; wait lms for display
        RETURN          ; done
```

LCD2 Source Code (continued)

```
; Table of fixed characters to send .....
Line1 ADDWF PCL          ; Modify program counter
      RETLW 'C'         ; Pointer = 0
      RETLW 'O'         ; Pointer = 1
      RETLW 'N'         ; Pointer = 2
      RETLW 'S'         ; Pointer = 3
      RETLW 'T'         ; Pointer = 4
      RETLW ':'         ; Pointer = 5
      RETLW '0'         ; Pointer = 6
      RETLW '1'         ; Pointer = 7
      RETLW '2'         ; Pointer = 8
      RETLW '3'         ; Pointer = 9
      RETLW '4'         ; Pointer = 10
      RETLW '5'         ; Pointer = 11
      RETLW '6'         ; Pointer = 12
      RETLW '7'         ; Pointer = 13
      RETLW '8'         ; Pointer = 14
      RETLW '9'         ; Pointer = 15

Line2 ADDWF PCL          ; Modify program counter
      RETLW 'V'         ; Pointer = 0
      RETLW 'A'         ; Pointer = 1
      RETLW 'R'         ; Pointer = 2
      RETLW 'I'         ; Pointer = 3
      RETLW 'A'         ; Pointer = 4
      RETLW 'B'         ; Pointer = 5
      RETLW 'L'         ; Pointer = 6
      RETLW 'E'         ; Pointer = 7
      RETLW ' '         ; Pointer = 8
      RETLW '='         ; Pointer = 9
      RETLW ' '         ; Pointer = 10

; Initialise the display.....
Init  MOVLW D'100'      ; Load count for 100ms delay
      CALL Xms          ; and wait for display start
      MOVLW 0F0         ; Mask for select code
      MOVWF Select     ; High nybble not masked

      MOVLW 0x30        ; Load initial nibble
      MOVWF PORTD      ; and output it to display
      CALL PulseE      ; Latch initial code
      MOVLW D'5'       ; Set delay 5ms
      CALL Xms         ; and wait
      CALL PulseE      ; Latch initial code again
      CALL Onems       ; Wait 1ms
      CALL PulseE      ; Latch initial code again
      BCF PORTD,4      ; Set 4-bit mode
      CALL PulseE      ; Latch it

      MOVLW 0x28        ; Set 4-bit mode, 2 lines
      CALL Send         ; and send code
      MOVLW 0x08        ; Switch off display
      CALL Send         ; and send code
      MOVLW 0x01        ; Code to clear display
      CALL Send         ; and send code
      MOVLW 0x06        ; Enable cursor auto inc
      CALL Send         ; and send code
      MOVLW 0x80        ; Zero display address
      CALL Send         ; and send code
      MOVLW 0x0C        ; Turn on display
      CALL Send         ; and send code

      RETURN           ; Done
```


LCD2 Source Code (continued)

; Send the fixed message to the display.....

```

OutMes CLRF   Point      ; Reset table pointer
      BSF    Select,RS  ; Select data mode

Mess1  MOVF   Point,W    ; and load it
      CALL  Line1      ; Get ASCII code from table
      CALL  Send       ; and do it
      INCF  Point      ; point to next character
      MOVF  Point,W    ; and load the pointer
      SUBLW D'16'      ; check for last table item
      BTFSS STATUS,Z   ; and finish if 16 done
      GOTO  Mess1      ; Output character code

      MOVLW 0xC0       ; Move cursor to line 2
      BCF   Select,RS  ; Select command mode
      CALL  Send       ; and send code
      CLRF  Point      ; Reset table pointer
Mess2  MOVF   Point,W    ; and load it
      CALL  Line2      ; Get fixed character
      BSF   Select,RS  ; Select data mode
      CALL  Send       ; and send code
      INCF  Point      ; next character
      MOVF  Point,W    ; Reload pointer
      SUBLW D'11'      ; and check for last
      BTFSS STATUS,Z   ; Skip if last
      GOTO  Mess2      ; or send next
      RETURN          ; done

```

; Output variable count to display (0-9) endlessly.....

```

OutVar CLRF   Var       ; Clear variable number
      MOVLW 0X30      ; Load offset to be added
      ADDWF Var       ; to make ASCII code (30-39)

Next   MOVF   Var,W     ; Load the code
      BSF    Select,RS ; Select data mode
      CALL  Send       ; and send code

      MOVLW 0xCB      ; code to move cursor back
      BCF   Select,RS ; Select command mode
      CALL  Send       ; and send code
      MOVLW D'250'    ; Load count to wait 250ms
      CALL  Xms       ; so numbers are visible

      INCF  Var       ; Next number
      MOVF  Var,W     ; Load number
      SUBLW 0x3A      ; Check for last (10=A)
      BTFSS STATUS,Z  ; and skip if last
      GOTO  Next      ; or do next number
      GOTO  OutVar    ; Repeat from number Z

```

; MAIN PROGRAM ;;

```

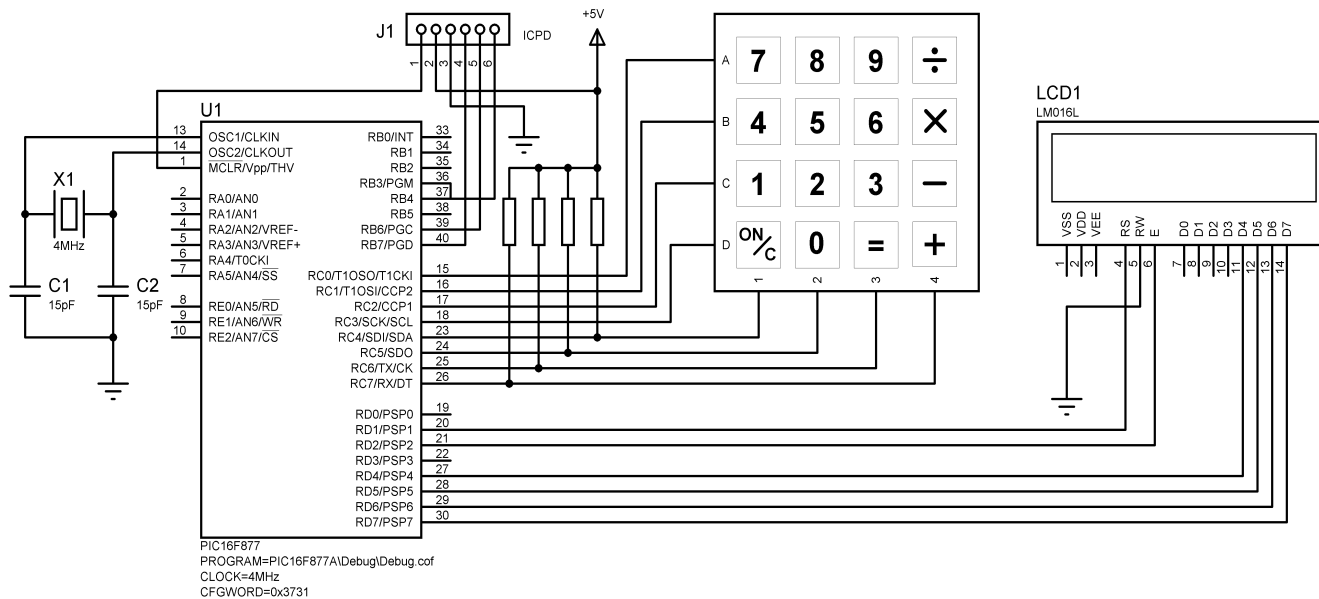
Start  CALL   Init      ; Initialise the display
      CALL  OutMes     ; Display fixed characters
      GOTO  OutVar     ; Display an endless count

      END              ; of source code

```

Interfacing PIC Microcontrollers

CALC2 Schematic



- This application demonstrates the basic principles of numerical processing using the keypad and LCD display
- It accepts two single digit integer inputs and performs an add, subtract, multiply or divide operation
- A two digit result is provided, with the division producing a result with an integer remainder
- The LCD driver routine is included as a separate source code file derived from the application LCD2 above

Interfacing PIC Microcontrollers

CALC2 Source Code

```
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
;
;   CALC2.ASM      MPB      12-01-13
;
;   Simple calculator
;   Single digit input, two digit results
;   Integer handling only
;   Updated for VSM v8
;
;
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

PROCESSOR 16F877
__CONFIG 0x3731          ; Clock = XT 4MHz

; LABEL EQUATES ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

INCLUDE "P16F877A.INC"

Char EQU 30      ; Display character code
Num1 EQU 31      ; First number input
Num2 EQU 32      ; Second number input
Result EQU 33    ; Calculated result
Oper EQU 34      ; Operation code store
Temp EQU 35      ; Temporary register for subtract
Kcount EQU 36    ; Count of keys hit
Kcode EQU 37     ; ASCII code for key
Msd EQU 38       ; Most significant digit of result
Lsd EQU 39       ; Least significant digit of result
Kval EQU 40      ; Key numerical value

RS EQU 1         ; Register select output bit
E EQU 2          ; Display data strobe

; Program begins ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

CODE 0           ; Default start address
NOP             ; required for ICD mode

BANKSEL TRISC   ; Select bank 1
MOVLW B'11110000' ; Keypad direction code
MOVWF TRISC     ;
CLRF TRISD      ; Display port is output

BANKSEL PORTC   ; Select bank 0
MOVLW OFF       ;
MOVWF PORTC     ; Set keypad outputs high
CLRF PORTD      ; Clear display outputs
GOTO start      ; Jump to main program
```

```
; MAIN LOOP ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

start CALL inid           ; Initialise the display
      MOVLW 0x80          ; position to home cursor
      BCF Select,RS       ; Select command mode
      CALL send           ; and send code

      CLRW Char           ; ASCII = 0
      CLRW Kval           ; Key value = 0
      CLRW DFlag         ; Digit flags = 0

scan  CALL keyin         ; Scan keypad
      MOVF Char,1        ; test character code
      BTFSS STATUS,Z     ; key pressed?
      GOTO keyon         ; yes - wait for release
      GOTO scan          ; no - scan again

keyon MOVF Char,W        ; Copy..
      MOVWF Kcode        ; ..ASCIIcode
      MOVLW D'50'        ; delay for..
      CALL xms           ; ..50ms debounce

wait  CALL keyin         ; scan keypad again
      MOVF Char,1        ; test character code
      BTFSS STATUS,Z     ; key pressed?
      GOTO wait          ; no - rescan
      CALL disout        ; yes - show symbol

      INCF Kcount        ; inc count..
      MOVF Kcount,W      ; ..of keys pressed
      ADDWF PCL           ; jump into table
      NOP
      GOTO first        ; process first key
      GOTO scan         ; get operation key
      GOTO second       ; process second symbol
      GOTO calc         ; calculate result
      GOTO clear        ; clear display

first MOVF Kval,W        ; store..
      MOVWF Num1        ; first num
      GOTO scan         ; and get op key

second MOVF Kval,W       ; store..
      MOVWF Num2        ; second number
      GOTO scan         ; and get equals key
```

CALC2 Source Code (continued)

```

;
SUBROUTINES ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
; Include LCD driver routine
    INCLUDE "LCD.INC"
; Scan
keypad .....

keyin  MOVLW  00F      ; deselect..
      MOVWF  PORTC    ; ..all rows
      BCF   PORTC,0   ; select row A
      CALL  onems     ; wait output stable

      BTFSC PORTC,4   ; button 7?
      GOTO  b8        ; no
      MOVLW '7'      ; yes
      MOVWF Char      ; load key code
      MOVLW 07       ; and
      MOVWF Kval      ; key value
      RETURN

b8     BTFSC  PORTC,5   ; button 8?
      GOTO  b9        ; no
      MOVLW '8'      ; yes
      MOVWF Char
      MOVLW 08
      MOVWF Kval
      RETURN

b9     BTFSC  PORTC,6   ; button 9?
      GOTO  bd        ; no
      MOVLW '9'      ; yes
      MOVWF Char
      MOVLW 09
      MOVWF Kval
      RETURN

bd     BTFSC  PORTC,7   ; button /?
      GOTO  rowb     ; no
      MOVLW '/'      ; yes
      MOVWF Char      ; store key code
      MOVWF Oper      ; store operator symbol
      RETURN

rowb   BSF   PORTC,0   ; select row B
      BCF   PORTC,1
      CALL  onems

      BTFSC  PORTC,4   ; button 4?
      GOTO  b5        ; no
      MOVLW '4'      ; yes
      MOVWF Char
      MOVLW 04
      MOVWF Kval
      RETURN

b5     BTFSC  PORTC,5   ; button 5?
      GOTO  b6        ; no
      MOVLW '5'      ; yes
      MOVWF Char
      MOVLW 05
      MOVWF Kval
      RETURN

b6     BTFSC  PORTC,6   ; button 6?
      GOTO  bm        ; no
      MOVLW '6'      ; yes
      MOVWF Char
      MOVLW 06
      MOVWF Kval
      RETURN

bm     BTFSC  PORTC,7   ; button x?
      GOTO  rowc     ; no
      MOVLW 'x'      ; yes
      MOVWF Char
      MOVWF Oper
      RETURN

```

CALC2 Source Code (continued)

```
rowc    BSF    PORTC,1    ; select row C
        BCF    PORTC,2
        CALL   onems

        BTFSC  PORTC,4    ; button 1?
        GOTO  b2          ; no
        MOVLW '1'        ; yes
        MOVWF Char
        MOVLW 01
        MOVWF Kval
        RETURN

b2      BTFSC  PORTC,5    ; button 2?
        GOTO  b3          ; no
        MOVLW '2'        ; yes
        MOVWF Char
        MOVLW 02
        MOVWF Kval
        RETURN

b3      BTFSC  PORTC,6    ; button 3?
        GOTO  bs         ; no
        MOVLW '3'        ; yes
        MOVWF Char
        MOVLW 03
        MOVWF Kval
        RETURN

bs      BTFSC  PORTC,7    ; button -?
        GOTO  rowd       ; no
        MOVLW '-'        ; yes
        MOVWF Char
        MOVWF Oper
        RETURN

rowd    BSF    PORTC,2    ; select row D
        BCF    PORTC,3
        CALL   onems

        BTFSC  PORTC,4    ; button C?
        GOTO  b0         ; no
        MOVLW 'c'        ; yes
        MOVWF Char
        MOVWF Oper
        RETURN

b0      BTFSC  PORTC,5    ; button 0?
        GOTO  be         ; no
        MOVLW '0'        ; yes
        MOVWF Char
        MOVLW 00
        MOVWF Kval
        RETURN

be      BTFSC  PORTC,6    ; button =?
        GOTO  bp         ; no
        MOVLW '='        ; yes
        MOVWF Char
        RETURN

bp      BTFSC  PORTC,7    ; button +?
        GOTO  done       ; no
        MOVLW '+'        ; yes
        MOVWF Char
        MOVWF Oper
        RETURN

done    BSF    PORTC,3    ; clear last row
        CLRF  Char       ; character code = 0
        RETURN
```

CALC2 Source Code (continued)

; Write display

```
disout  MOVF    Kcode,W      ; Load the code
        BSF     Select,RS    ; Select data mode
        CALL    send        ; and send code
        RETURN
```

; Process operations

```
calc    MOVF    Oper,W      ; check for add
        MOVWF   Temp        ; load input op code
        MOVLW  '+'         ; load plus code
        SUBWF  Temp        ; compare
        BTFSC  STATUS,Z    ; and check if same
        GOTO   add         ; yes, jump to op

        MOVF    Oper,W      ; check for subtract
        MOVWF   Temp        ; load input op code
        MOVLW  '-'         ; load minus code
        SUBWF  Temp        ; compare
        BTFSC  STATUS,Z    ; and check if same
        GOTO   sub         ; yes, jump to op

        MOVF    Oper,W      ; check for multiply
        MOVWF   Temp        ; load input op code
        MOVLW  'x'         ; load multiply code
        SUBWF  Temp        ; compare
        BTFSC  STATUS,Z    ; and check if same
        GOTO   mul         ; yes, jump to op

        MOVF    Oper,W      ; check for divide
        MOVWF   Temp        ; load input op code
        MOVLW  '/'         ; load divide code
        SUBWF  Temp        ; compare
        BTFSC  STATUS,Z    ; and check if same
        GOTO   div         ; yes, jump to op
        GOTO   scan        ; rescan if key invalid
```

; Calculate results from 2 input numbers

```
add     MOVF    Num1,W      ; get first number
        ADDWF   Num2,W      ; add second
        MOVWF   Result     ; and store result
        GOTO   outres      ; display result

sub     BSF     STATUS,C    ; Negative detect flag
        MOVF    Num2,W      ; get first number
        SUBWF   Num1,W      ; subtract second
        MOVWF   Result     ; and store result

        BTFSS  STATUS,C    ; answer negative?
        GOTO   minus       ; yes, minus result
        GOTO   outres      ; display result

minus   MOVLW  '-'         ; load minus sign
        BSF     Select,RS    ; Select data mode
        CALL    send        ; and send symbol

        COMF   Result     ; invert all bits
        INCF   Result     ; add 1
        GOTO   outres      ; display result

mul     MOVF    Num1,W      ; get first number
        CLRF   Result     ; total to Z
        ADDWF  Result     ; add to total
        DECFSZ Num2        ; num2 times and
        GOTO   add1        ; repeat if not done
        GOTO   outres      ; done, display result

add1    ADDWF   Result     ; add to total
        DECFSZ Num2        ; num2 times and
        GOTO   add1        ; repeat if not done
        GOTO   outres      ; done, display result
```

CALC2 Source Code (continued)

```

div    CLRF    Result    ; total to Z
      MOVF    Num2,W    ; get divisor
      BCF    STATUS,C   ; set C flag
sub1   INCF    Result    ; count loop start
      SUBWF   Num1      ; subtract
      BTFSS  STATUS,Z   ; exact answer?
      GOTO   neg        ; no
      GOTO   outres     ; yes, display answer
neg    BTFSC  STATUS,C   ; gone negative?
      GOTO   sub1       ; no - repeat
      DECF   Result    ; correct the result
      MOVF   Num2,W    ; get divisor
      ADDWF  Num1      ; calc remainder

      MOVF   Result,W  ; load result
      ADDLW  030       ; convert to ASCII
      BSF   Select,RS  ; Select data mode
      CALL  send       ; and send result

      MOVLW  'r'       ; indicate remainder
      CALL  send
      MOVF   Num1,W    ; convert to ASCII
      ADDLW  030
      CALL  send
      GOTO  scan

; Convert binary to BCD .....

outres MOVF    Result,W  ; load result
      MOVWF  Lsd        ; into low digit store
      CLRF  Msd         ; high digit = 0
      BSF   STATUS,C   ; set C flag
      MOVLW D'10'      ; load 10

again  SUBWF  Lsd        ; sub 10 from result
      INCF  Msd         ; inc high digit
      BTFSC STATUS,C   ; check if negative
      GOTO  again      ; no, keep going
      ADDWF Lsd        ; yes, add 10 back
      DECF  Msd         ; inc high digit

; display 2 digit BCD result .....
      MOVF   Msd,W      ; load high digit result
      BTFSC  STATUS,Z   ; check if Z
      GOTO   low        ; yes, dont display Msd

      ADDLW  030        ; convert to ASCII
      BSF   Select,RS  ; Select data mode
      CALL  send        ; and send Msd

low    MOVF   Lsd,W     ; load low digit result
      ADDLW  030        ; convert to ASCII
      BSF   Select,RS  ; Select data mode
      CALL  send        ; and send Msd

      GOTO  scan        ; scan for clear key

; Restart .....

clear  MOVLW  01        ; code to clear display
      BCF   Select,RS  ; Select data mode
      CALL  send        ; and send code
      CLRF  Kcount     ; reset count of keys
      GOTO  scan        ; and rescan keypad

      END              ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

```

CALC2 Source Code (continued)

```

-----
;
; LCD.INC MPB 19-12-05
;
; Include file to operate 16x2 LCD display
; Uses GPR 70 - 75
;
; Final version
-----

Timer1 EQU 70 ; lms count register
TimerX EQU 71 ; Xms count register
Var EQU 72 ; Output variable
Point EQU 73 ; Program table pointer
Select EQU 74 ; Used to set or clear RS bit
OutCod EQU 75 ; Temp store for output code

RS EQU 1 ; Register select output bit
E EQU 2 ; Enable display input

-----
;
; lms delay with lus cycle time (1000 cycles)
-----
onems MOV LW D'249' ; Count for lms delay
MOV W Timer1 ; Load count
loop1 NOP ; Pad for 4 cycle loop
DECFSZ Timer1 ; Count
GOTO loop1 ; until Z
RETURN ; and finish

-----
;
; Delay Xms
; Receives count in W, uses Onems
-----
xms MOV W TimerX ; Count for X ms
loopX CALL onems ; Delay lms
DECFSZ TimerX ; Repeat X times
GOTO loopX ; until Z
RETURN ; and finish

-----
;
; Generate data/command clock siganl E
-----
pulseE BSF PORTD,E ; Set E high
CALL onems ; Delay lms
BCF PORTD,E ; Reset E low
CALL onems ; Delay lms
RETURN ; done

```

```

-----
;
; Send a command byte in two nibbles from RB4 - RB7
; Receives command in W, uses PulseE and Onems
-----
send MOV W OutCod ; Store output code
ANDLW 0F0 ; Clear low nybble
MOV W PORTD ; Output high nybble
BTFSC Select,RS ; Test RS bit
BSF PORTD,RS ; and set for data
CALL pulseE ; and clock display register
CALL onems ; wait lms for display

SWAPF OutCod ; Swap low and high nybbles
MOV W OutCod,W ; Retrieve output code
ANDLW 0F0 ; Clear low nybble
MOV W PORTD ; Output low nybble
BTFSC Select,RS ; Test RS bit
BSF PORTD,RS ; and set for data
CALL pulseE ; and clock display register
CALL onems ; wait lms for display
RETURN ; done

-----
;
; Initialise the display
; Uses Send
-----
inid MOV LW D'100' ; Load count for 100ms delay
CALL xms ; and wait for display start
MOV LW 0F0 ; Mask for select code
MOV W Select ; High nybble not masked

MOV LW 0x30 ; Load initial nibble
MOV W PORTD ; and output it to display
CALL pulseE ; Latch initial code
MOV LW D'5' ; Set delay 5ms
CALL xms ; and wait
CALL pulseE ; Latch initial code again
CALL onems ; Wait lms
CALL pulseE ; Latch initial code again
BCF PORTD,4 ; Set 4-bit mode
CALL pulseE ; Latch it

MOV LW 0x28 ; Set 4-bit mode, 2 lines
CALL send ; and send code
MOV LW 0x08 ; Switch off display
CALL send ; and send code
MOV LW 0x01 ; Code to clear display
CALL send ; and send code
MOV LW 0x06 ; Enable cursor auto inc
CALL send ; and send code
MOV LW 0x80 ; Zero display address
CALL send ; and send code
MOV LW 0x0C ; Turn on display
CALL send ; and send code

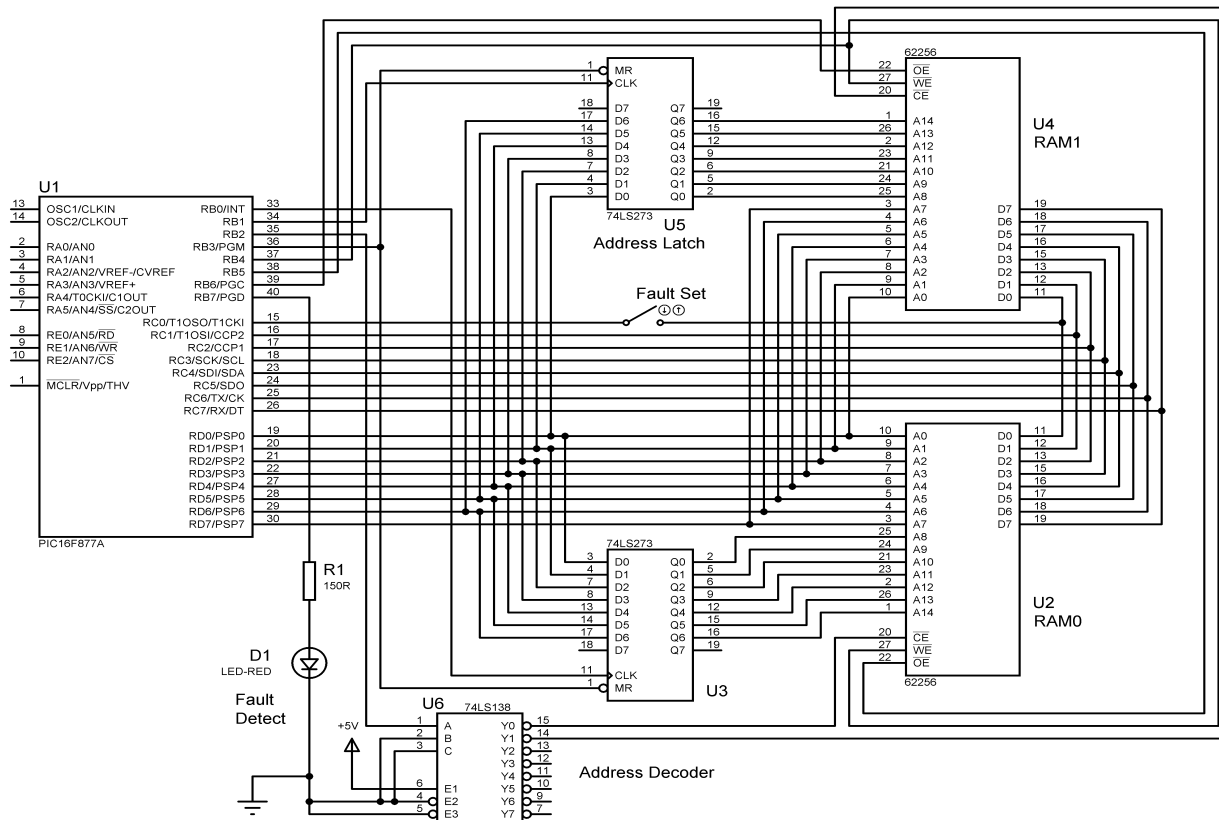
RETURN ; Done

-----

```


Interfacing PIC Microcontrollers

PARMEM2 Schematic



- This application demonstrates parallel memory expansion
- A pair of 32k RAM chips are used that have 8-bit data I/O ports and 15-bit address inputs
- Address latches are used to store the address high byte so that only 8 PIC data lines are needed
- The address decoder selects the RAM chip to be accessed
- A switch in the LSB data line simulated a faulty data access

Interfacing PIC Microcontrollers

PARMEM2 Source Code

```
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
;   PARMEM.ASM      MPB      Ver:2.0      18-02-13
;.....
;
;   Parallel memory system
;   PIC 16F877A operates with expansion memory
;   RAM = 2 x 62256 32kb
;   Updated for VSM v8
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

PROCESSOR 16F877A      ; define MPU
__CONFIG 0x3731        ; XT clock
INCLUDE "P16F877A.INC"; Standard register labels

ConReg EQU    06      ; Port B = Control Register
DatReg EQU    07      ; Port C = Data Register
AddReg EQU    08      ; Port D = Address Register
HiAdd EQU    20      ; High address store

CLK0 EQU    0      ; RAM0 address buffer clock
CLK1 EQU    1      ; RAM1 address buffer clock
SelRAM EQU    2      ; RAM select bit
ResHi EQU    3      ; High address reset bit
WritEn EQU    4      ; Write enable bit
OutEn0 EQU    5      ; Output enable bit RAM0
OutEn1 EQU    6      ; Output enable bit RAM1
LED EQU    7      ; Memory error indicator

; Initialise ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

CODE 0      ; Place machine code

NOP      ; Required for ICD mode

BANKSEL TRISB      ; Select bank 1
CLRF TRISB      ; Control output bits
CLRF TRISC      ; Data bus initially output
CLRF TRISD      ; Address bus output

BANKSEL AddReg      ; Select bank 0
CLRF DatReg      ; Clear outputs initially
CLRF AddReg      ; Clear outputs initially
BCF ConReg,CLK0      ; RAM0 address buffer clock
BCF ConReg,CLK1      ; RAM1 address buffer clock
BCF ConReg,SelRAM      ; Select RAM0 initially
BCF ConReg,ResHi      ; Reset high address latches
BSF ConReg,OutEn0      ; Disable output enable RAM0
BSF ConReg,OutEn1      ; Disable output enable RAM1
BSF ConReg,WritEn      ; Disable write enable bit
BCF ConReg,LED      ; Switch of error indicator
```

```
; MAIN LOOP ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

start CALL write      ; test write to memory
CALL read      ; test read from memory
SLEEP      ; shut down

; Write checkerboard pattern to both RAMs ;;;;;;;;;;;;;;;;;;;;;;;;;;

write BSF ConReg,ResHi      ; Enable address latches
nexwrt MOVLW 055      ; checkerboard test data
MOVWF DatReg      ; output on data bus
CALL store      ; and write to RAM
MOVLW 0AA      ; checkerboard test data
MOVWF DatReg      ; output on data bus
CALL store      ; and write to RAM
BTFSS ConReg,ResHi      ; all done?
RETURN      ; yes - quit
GOTO nexwrt      ; no - next byte pair

; Check data stored ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

read NOP      ; required for label
BANKSEL TRISC      ; select bank 1
MOVLW 0FF      ; all inputs..
MOVWF TRISC      ; ..at Port C

BANKSEL ConReg      ; select default bank 0
BSF ConReg,ResHi      ; Enable address latches
BCF ConReg,SelRAM      ; select RAM0
BCF ConReg,OutEn0      ; set RAM0 for output
CALL nexred      ; check data in RAM0
BSF ConReg,SelRAM      ; select RAM0
BCF ConReg,OutEn1      ; set RAM0 for output
CALL nexred      ; check data in RAM0
RETURN      ; all done

; Load test data and check data .....

nexred MOVLW 055      ; load even data byte
CALL test      ; check data
MOVLW 0AA      ; load odd data byte
CALL test      ; check data
BTFSS ConReg,ResHi      ; all done?
RETURN      ; yes - quit
GOTO nexred      ; no - next byte pair
```

PARMEM2 Source Code (continued)

```
; Write data to RAM .....
store  BCF    ConReg,SelRAM ; no - Select RAM0
       BCF    ConReg,WritEn ; negative pulse ..
       BSF    ConReg,WritEn
       BSF    ConReg,SelRAM ; Select RAM1
       BCF    ConReg,WritEn ; negative pulse ..
       BSF    ConReg,WritEn ; ..write bit
       INCF   AddReg        ; next address
       BTFSC  STATUS,Z      ; last address?
       CALL   inchi         ; yes - increment high address
       RETURN                ; no - next byte

; Test memory data .....
test   MOVF   DatReg,F      ; read data
       SUBWF  DatReg,W      ; compare data
       BTFSS  STATUS,Z      ; same?
       BSF    ConReg,LED    ; no - switch on LED
       INCF   AddReg        ; yes - next address
       BTFSC  STATUS,Z      ; last address in block?
       CALL   inchi         ; yes - increment high address
       RETURN                ; no - continue

; Select next block of RAM .....
inchi  INCF   HiAdd         ; next block
       BTFSC  STATUS,Z      ; all done?
       GOTO   alldon        ; yes
       MOVF   HiAdd,W       ; no - load high address
       MOVWF  AddReg        ; output it
       BSF    ConReg,CLK0   ; clock it into latches
       BSF    ConReg,CLK1
       BCF    ConReg,CLK0
       BCF    ConReg,CLK1
       CLRF   AddReg        ; reset low address to zero
       RETURN                ; block done
alldon BCF    ConReg,ResHi   ; reset address latches
       RETURN                ; all blocks done

END    ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
```